

Developing Disciplined Programs

Seminar at Appalachian State University

Clément Aubert

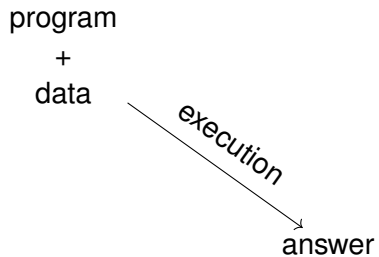


6th February 2017

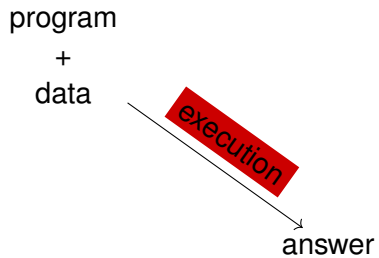
program

program
+
data

Introduction: What is the problem with my program?

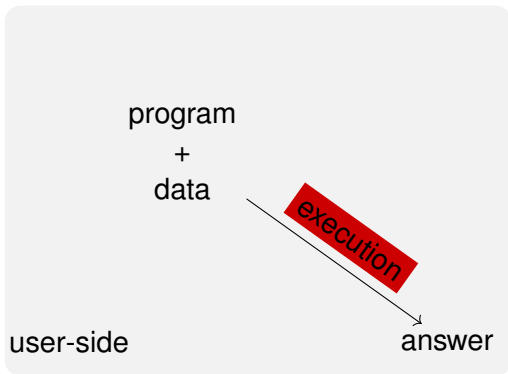


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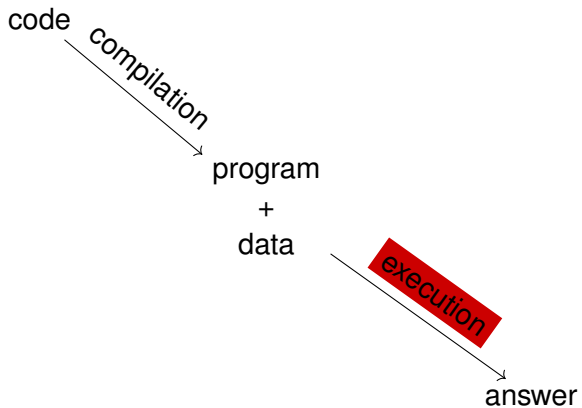


Introduction: What is the problem with my program?

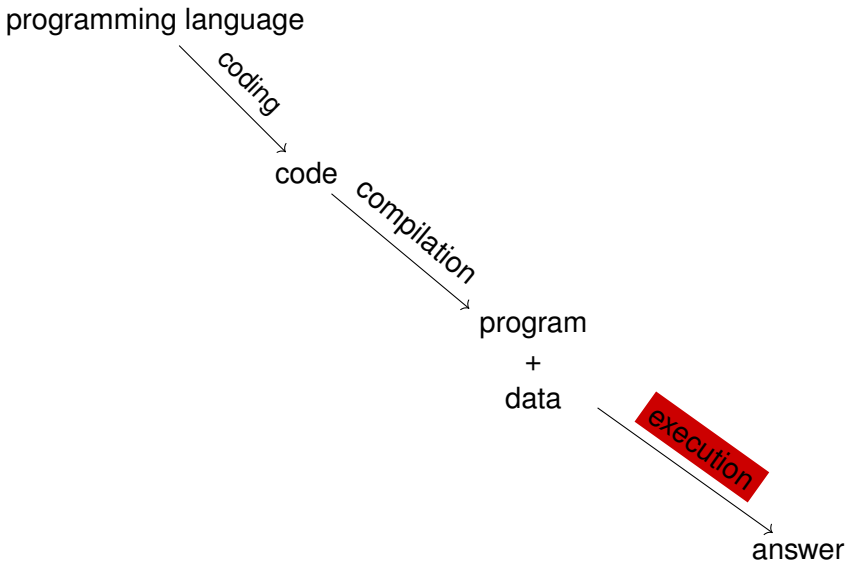
- operating system
- network
- hardware



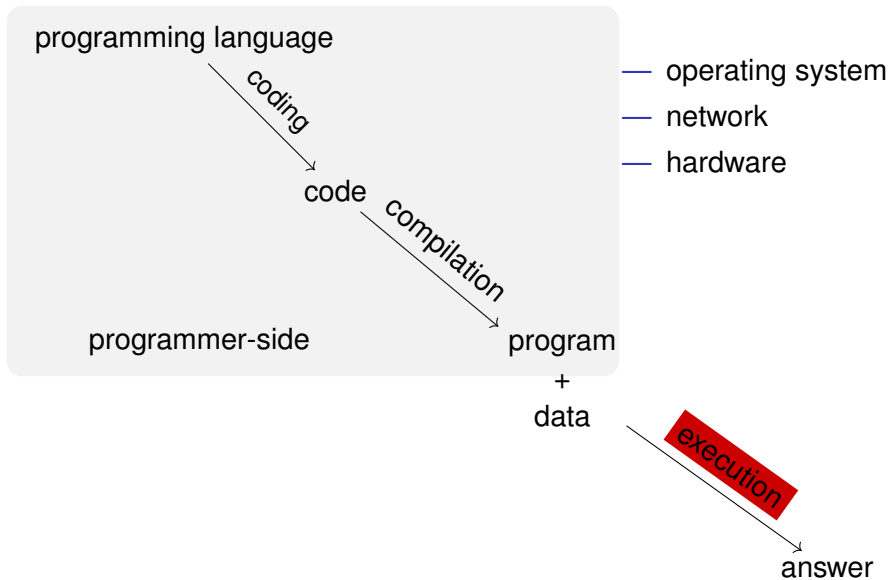
Introduction: What is the problem with my program?



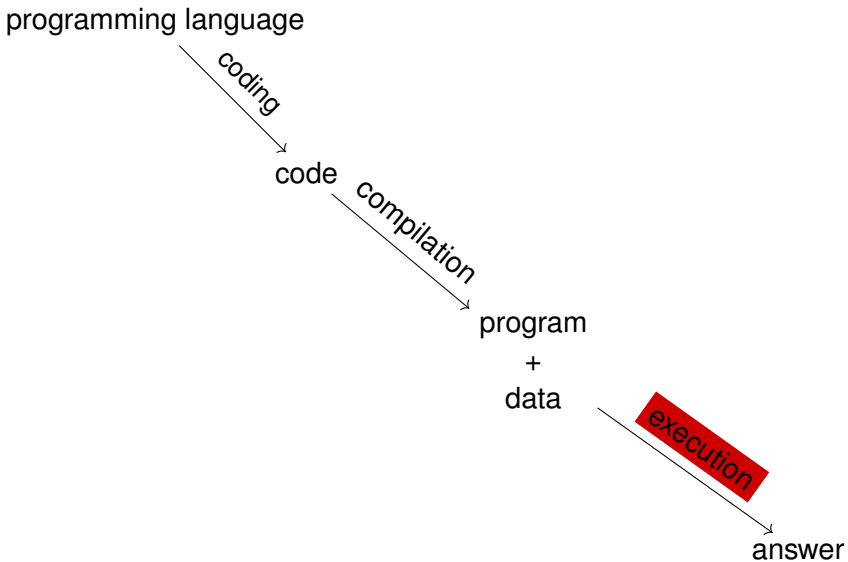
Introduction: What is the problem with my program?



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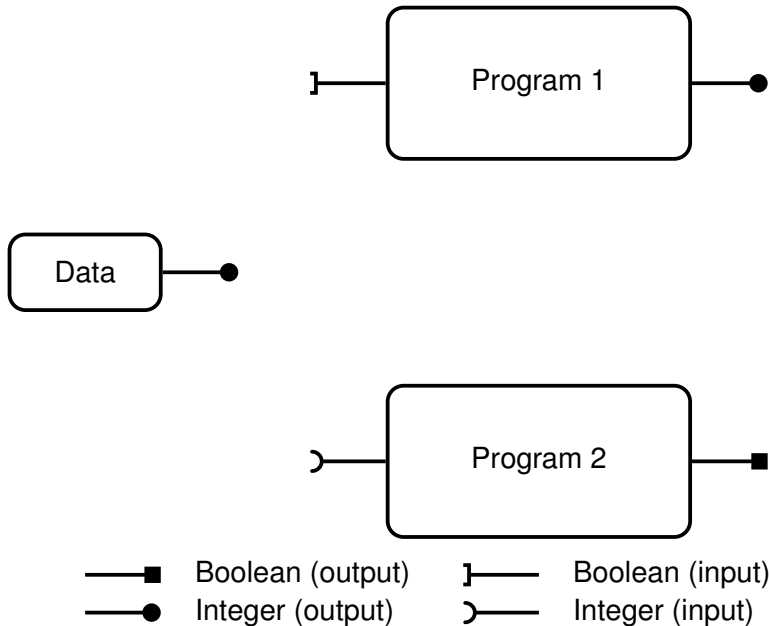
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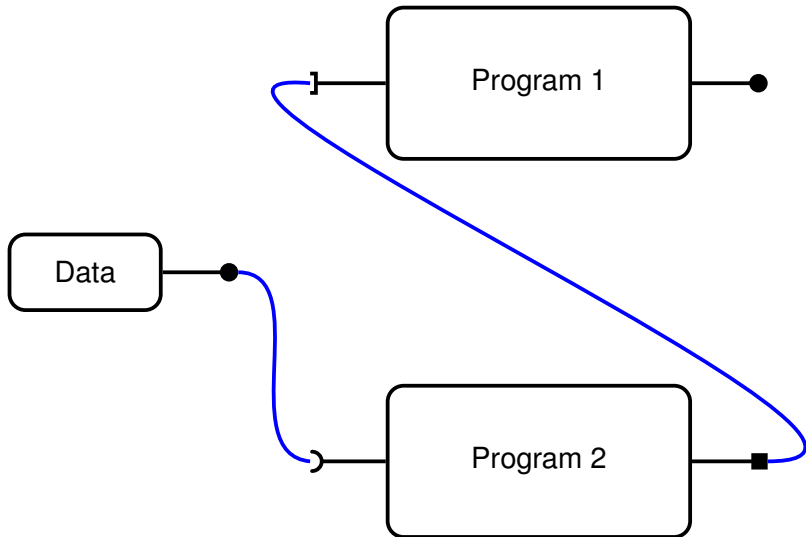
Developing Disciplined *Programing Languages*
Seminar at Appalachian State University

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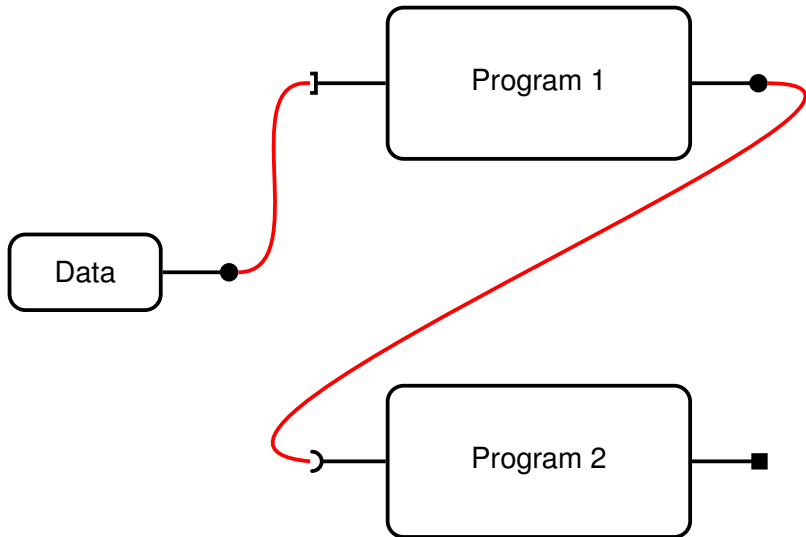


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- | | | | |
|----|------------------|----|-----------------|
| —■ | Boolean (output) | ┌— | Boolean (input) |
| —● | Integer (output) | └— | Integer (input) |



- | | | | |
|----|------------------|----|-----------------|
| —■ | Boolean (output) |]— | Boolean (input) |
| —● | Integer (output) | ⌋— | Integer (input) |

$$\frac{\begin{array}{c} \vdash \text{Program 1} : \text{Bool} \rightarrow \text{Int} \\ \vdash \text{Program 2} : \text{Int} \rightarrow \text{Bool} \quad \vdash \text{data} : \text{Int} \\ \hline \vdash \text{Program 2 (data)} : \text{Bool} \end{array}}{\vdash \text{Program1 (Program 2 (data))} : \text{Int}}$$

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↙

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$$\Downarrow$$

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$$\Downarrow$$

$$\frac{\vdash_x \text{Bool} \rightarrow \text{Int} \quad \frac{\vdash_y \text{Int} \rightarrow \text{Bool} \quad \vdash_z \text{Int}}{\vdash_{y+z+c} \text{Bool}}}{\vdash_{y+z+c+x+c'} \text{Int}}$$

Computational Complexity

- Sort problem by their difficulty

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- Order of magnitude

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- Benchmark: Turing Machine

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Complete Problems

Logarithmic Space (**L**): Acyclicity in undirected graph

Non-Deterministic Logarithmic Space (**NL**): Acyclicity in directed graph

Polynomial Time (**Ptime**): Circuit value problem

Explicit Computational Complexity

- Sort problem by their difficulty
- Order of magnitude
- Benchmark: Turing Machine

Complete Problems

Logarithmic Space (**L**): Acyclicity in undirected graph

Non-Deterministic Logarithmic Space (**NL**): Acyclicity in directed graph

Polynomial Time (**Ptime**): Circuit value problem

- Machine-dependent
- “External” clock and “external” measure on the tape

classes. By implicit, we here mean that classes are not given by constraining the amount of resources a *machine* is allowed to use, but rather by imposing linguistic constraints on the way *algorithms* are formulated. This idea has de-

(Dal Lago, 2011, p. 90)(lacl.fr/~caubert/ASU/sm.html)

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Implicit Computational Complexity (ICC)

- Machine-independent
- Without explicit bounds

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Implicit Computational Complexity (ICC)

- Machine-independent
- Without explicit bounds

Some Achievements

- Fine-grained type systems for **Ptime**, **L**, **NL**, **Pspace**, etc.
- Differential privacy (Gaboardi et al., 2013)
- Computation over the reals (Férée et al., 2015)



1 Introduction

What is the problem with my program?

Type Theory

Computational Complexity

Implicit Computational Complexity

2 ICC, Automata & Logic Programs

3 A New Correspondence

4 Perspectives





- 1 Introduction
- 2 ICC, Automata & Logic Programs
 - What is ICC, really?
 - Automata
 - Logic Programming
- 3 A New Correspondence
- 4 Perspectives



Machine-dependent

Turing machine,
Random access machine,
Counter machine, ...

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The rules for storage naturally induce polynomials:

$$\text{Storage} \quad \frac{!_y \Gamma \vdash A}{!_{xy} \Gamma \vdash !_x A}$$

$$\text{Weakening} \quad \frac{\Gamma \vdash B}{\Gamma, !_0 A \vdash B}$$

$$\text{Contraction} \quad \frac{\Gamma, !_x A, !_y A \vdash B}{\Gamma, !_x A \vdash B}$$

$$\text{Dereliction} \quad \frac{\Gamma, A \vdash B}{\Gamma, !_1 A \vdash B}$$

(Girard et al., 1992, p. 18)

Explicit bounds

Machine-dependent

Turing machine,
Random access machine,
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Bounded recursion on notation (Cobham, 1965),
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	Machine-dependent	Machine-independent
Explicit bounds	Turing machine, Random access machine, Counter machine, ...	Bounded recursion on notation (Cobham, 1965), Bounded linear logic (Girard et al., 1992), Bounded arithmetic (Buss, 1986), ...
Implicit bounds		Descriptive complexity (Fagin, 1973), Recursion on notation (Bellantoni and Cook, 1992), Tiered recurrence (Leivant, 1993), ...

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Implicit bounds	Automaton, Auxiliary pushdown machine, ...	Descriptive complexity (Fagin, 1973), Recursion on notation (Bellantoni and Cook, 1992), Tiered recurrence (Leivant, 1993), ...

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bounds	Automaton, Auxiliary pushdown machine.	Descriptive complexity (Fagin, 1973), Recursion on notation (Bellantoni and Cook, 1992),

related to the foregoing question. More specifically, we have attempted to characterize several tape and time complexity classes of Turing machines in terms of devices whose definitions involve only ways in which their infinite memory may be manipulated and no restrictions are imposed on the amount of memory that they use. The basic model

(Ibarra, 1971, p. 88)

2NFA(k, p)

— Automata

$2\text{NFA}(k, p)$

- Automata
- + Non-Deterministic

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- Automata
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- + with $p \geq 0$ pushdown stacks

$2\text{NFA}(k, p)$

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- + 2-ways

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2NFA(k, p)

- Automata
- + Non-Deterministic
- + with $p \geq 0$ pushdown stacks
- + 2-ways
- + with $k \geq 1$ heads.

Main characterizations

Automata	Language / Predicate
2NFA(1, 0)	Regular
2NFA(1, 1)	Context-free
2NFA(*, 0)	Non-Deterministic Logarithmic space (NL)
2NFA(*, 1)	Polynomial time (Ptime)
2NFA(1, 2)	Computable

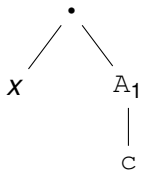
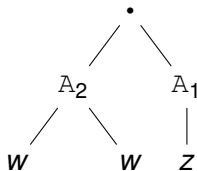
Logic Programming

- A programming paradigm
- Computation = unification
- Turing-complete

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Example

 $x \cdot A_1(c)$

 $A_2(w, w) \cdot A_1(z)$


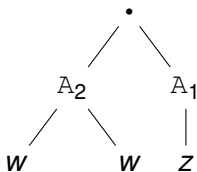
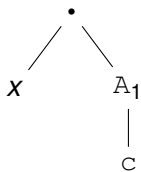
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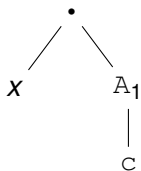
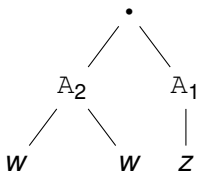
Unifiable?



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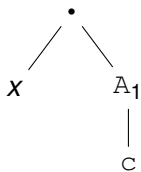
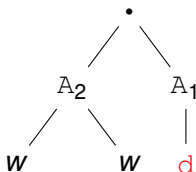
Unifiable?


 $\theta = [x \leftarrow A_2(w, w); z \leftarrow c]$

Logic Programming

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Example

 $x \cdot A_1(c)$  $A_2(w, w) \cdot A_1(d)$ 

Unifiable?

✗

 $c \neq d$

Logic Programming

- A programming paradigm
- Computation = unification
- Turing-complete

Used in ...

- Prolog, Datalog
- Type-inference in Haskell and ML
- Models of Linear Logic (Baillot and Pedicini, 2001; Girard, 2013)

Flows

A *flow* is a pair of terms $t \leftarrow u$ with $\text{Var}(t) \subseteq \text{Var}(u)$.

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Balanced

A flow $t \leftarrow u$ is *balanced* if for any $x \in \text{Var}(t) \cup \text{Var}(u)$, all occurrences of x in both t and u have the same height.

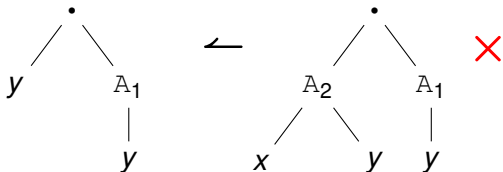
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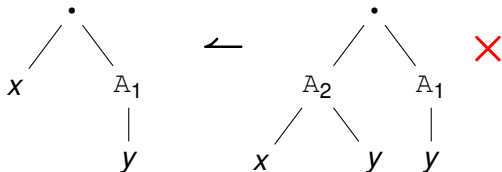
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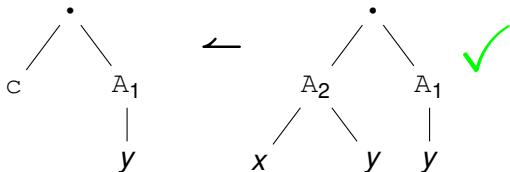
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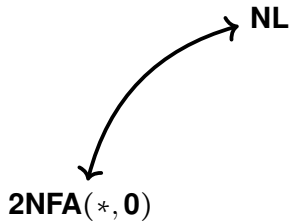
Unary

A flow is *unary* if it is built using only unary function symbols and a variable.

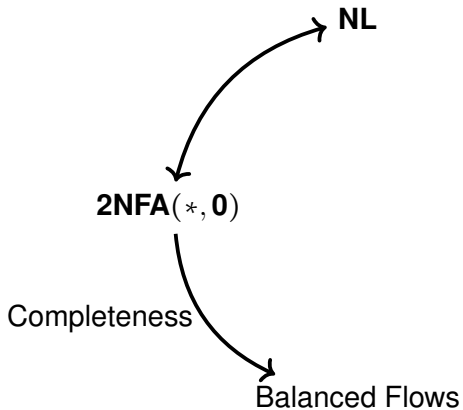


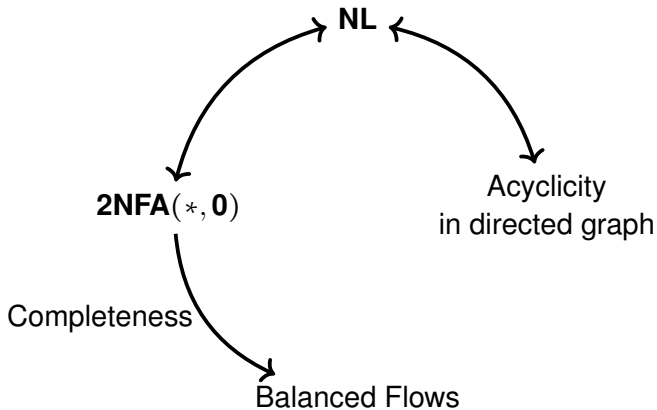
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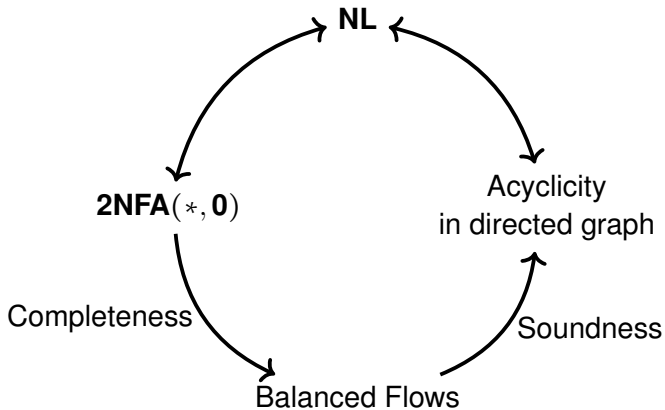


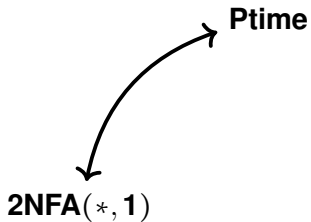


Balanced Flows

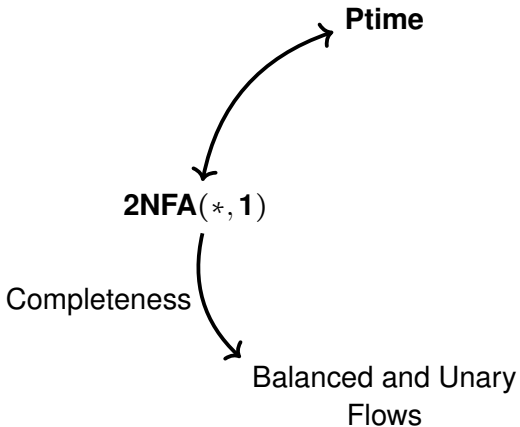


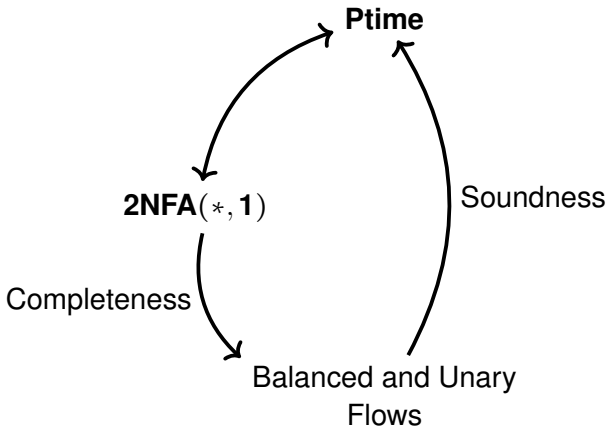


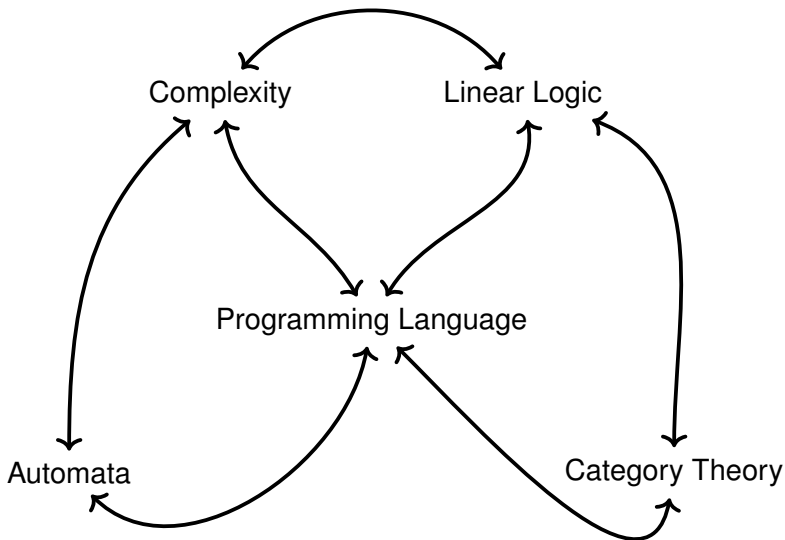




Balanced and Unary
Flows







In increasing order of complexity:

- Write an interpreter for Automata (Chakraborty, Saxena, and Katti, 2011)

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- Knowledge transfers

In increasing order of complexity:

- Write an interpreter for Automata (Chakraborty, Saxena, and Katti, 2011)
- The odd status of inputs
- Knowledge transfers
- Encode other variations of automata

Classroom Presentation lacl.fr/~caubert/ASU/cp.html

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Reversibility is in embryonic stage:

- Interpreter for reversible automata
- Extending `Janus`' datatypes and datastructures
- Reversible algorithms 101
- Software engineering on research code
- New programming languages

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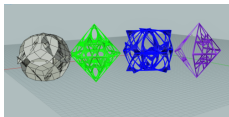
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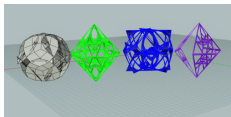
Benefits:

- Re-usable skills
- Small community = strong (international) impact
- So much to be done!

- Alisha Sprinkle + Richard Elaver (Assistant Professor of Industrial Design) =

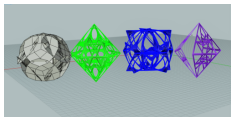


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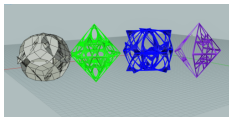
- ? + Richard Elaver = Python to design

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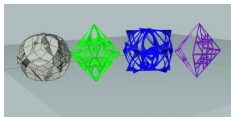
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- ? + Richard Elaver = Python to design
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Thanks!



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