

Using Stochastic Comparison for Efficient Model Checking of Uncertain Markov Chains ¹

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Motivation

From probabilistic discrete-event systems to Markov chains (MCs)

- ▶ Probabilistic systems are not necessarily memoryless (timeouts, packet arrivals, etc.).
- ▶ However during the modeling and analysis process, one often encounters Markov chains (e.g. the embedded Markov chain of a semi-Markovian process).

Why Interval Markov Chains (IMCs)?

- ▶ Estimation of the transition rates through statistical experiences leading to confidence intervals.
- ▶ Abstraction of events during the modeling step or abstraction of states during the analysis step.

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Analysis of IMC

First works

- ▶ Introduction of the formalism and study of conformance relations between models.
(*Jonsson, Larsen LCS'91*)
- ▶ Methods for computing the parameters of an IMC.
(*Kozine, Utkin Reliable Computing 2002*)

Probabilistic model-checking

- ▶ Analysis of the model checking of PCTL over IMCs: in PSPACE (via the existential theory of reals), NP-hard and coNP-hard.
(*Sen, Wiswanathan, Agha TACAS'06*)
- ▶ Generalization for a new logic ω -PCTL: still in PSPACE.
(*Chatterjee, Sen, Henzinger FOSSACS'08*).

Handling efficiently model checking for IMC

Drawbacks: complexity and expressivity considerations

- ▶ Algorithms in PSPACE are impractical for large IMCs.
- ▶ Some useful properties cannot be expressed even with ω -PCTL.

Goal: semi-decision procedures based on stochastic comparison

- ▶ Generally different magnitude orders between the requirement and implementation probabilities.
Thus the *don't know* case should seldom occur.
- ▶ The problem is reduced to the model checking of MCs.
This should lead to a significant improvement w.r.t. time complexity.

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Outline

- 1 IMC model
- 2 PCTL
- 3 Efficient Model Checking PCTL for IMCs
- 4 Conclusion and perspectives

Outline

① IMC model

PCTL

Efficient Model Checking PCTL for IMCs

Conclusion and perspectives

Interval Markov Chain

Syntax

An IMC $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+) = (\mathcal{S}, \mathbf{P}^-, \mathbf{P}^+, L)$ is defined by:

- ▶ \mathcal{S} , the finite set of states which are labelled by atomic properties through the mapping L ;
- ▶ \mathbf{P}^- (resp. \mathbf{P}^+ with $\mathbf{P}^+ \geq \mathbf{P}^-$), a sub-stochastic (resp. super-stochastic) matrix:

$$\forall s \in \mathcal{S} \quad \sum_{t \in \mathcal{S}} \mathbf{P}^- [s, t] \leq 1 \leq \sum_{t \in \mathcal{S}} \mathbf{P}^+ [s, t]$$

Semantic

A DTMC with transition probability matrix \mathbf{P} over \mathcal{S} is said to belong to $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+)$ (denoted $\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+)$), if:

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W.l.o.g. we assume that:

$$\mathbf{P}^- [s, t] \geq 1 - \sum_{t' \neq t} \mathbf{P}^+ [s, t'] \wedge \mathbf{P}^+ [s, t] \leq 1 - \sum_{t' \neq t} \mathbf{P}^- [s, t']$$

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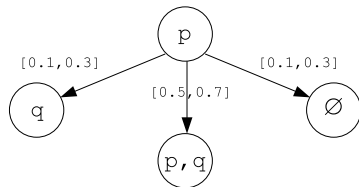
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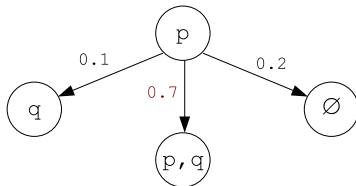
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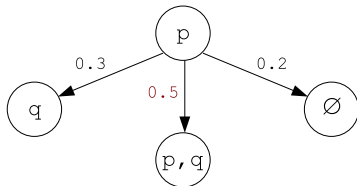
An IMC with two associated DTMCs



Maximizing a probability transition



Minimizing a probability transition



Optimal values for cumulative transition probabilities

Individual transition probabilities

Bounds can always be reached. For every $s, t \in \mathcal{S}$, there is a $\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+)$ with $\mathbf{P}[s, t] = \mathbf{P}^+[s, t]$ and a $\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+)$ with $\mathbf{P}[s, t] = \mathbf{P}^-[s, t]$.

Let $s \in \mathcal{S}$ and $\mathcal{S}' = \{s_1, \dots, s_m\} \subset \mathcal{S} = \{s_1, \dots, s_n\}$

How to maximize $\sum_{t \in \mathcal{S}'} \mathbf{P}[s, t]$ for possible \mathbf{P} in $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+)$?

- ▶ Maximize one by one the probability transition taking into account the constraints updated by the previous choices.
- ▶ More formally, let $sum = \sum_{j < i} \mathbf{P}[s, s_j]$. Then:
$$\mathbf{P}[s, s_i] = \min(\mathbf{P}^+[s, s_i], 1 - sum - \sum_{j > i} \mathbf{P}^-[s, s_j]);$$

Observations

- ▶ There is a similar algorithm for minimization.
- ▶ Different subrows $\mathbf{P}[s, -]$ are possible depending on the ordering of \mathcal{S}' .

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IMC for sub-stochastic matrices

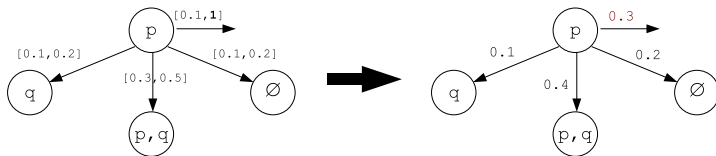
When model checking MCs, one produces MCs with an absorbing state or equivalently sub-stochastic matrices. So:

An IMC $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \mathbf{out})$ for sub-stochastic matrices is enlarged with a vector \mathbf{out} over states such that $\mathbf{P}^-, \mathbf{P}^+, \mathbf{out}$ fulfill for all $s, t \in \mathcal{S}$:

- ▶ $0 \leq \mathbf{P}^-[s, t] \leq \mathbf{P}^+[s, t] \wedge \sum_{t' \in \mathcal{S}} \mathbf{P}^-[s, t'] + \mathbf{out}[s] \leq 1$
- ▶ $\mathbf{P}^+[s, t] \leq 1 - \sum_{t' \neq t} \mathbf{P}^-[s, t'] - \mathbf{out}[s]$

A sub-stochastic matrix \mathbf{P} over \mathcal{S} belongs to $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \mathbf{out})$ if:

$$\forall s, t \in \mathcal{S} \quad \mathbf{P}^-[s, t] \leq \mathbf{P}[s, t] \leq \mathbf{P}^+[s, t] \wedge \sum_{t' \neq t} \mathbf{P}[s, t'] \leq 1 - \mathbf{out}[s]$$



Stochastic bounds

The survival toolkit: definitions

- ▶ Let X, Y be two defective distributions over $\mathcal{S} = \{s_1, \dots, s_n\}$ defined by $p_X(i) = \text{prob}(X = s_i)$ and $p_Y(i) = \text{prob}(Y = s_i)$. Then:

$$X \leq_{st} Y \text{ if } \forall i \sum_{k=1}^i p_X(k) \geq \sum_{k=1}^i p_Y(k)$$

- ▶ Let \mathbf{P}, \mathbf{P}' be two sub-stochastic matrices over \mathcal{S} . Then:

$$\mathbf{P} \leq_{st} \mathbf{P}' \text{ if } \forall i \mathbf{P}[s_i, -] \leq_{st} \mathbf{P}'[s_i, -]$$

- ▶ Let \mathbf{P} be a sub-stochastic matrix over \mathcal{S} . Then:

$$\mathbf{P} \text{ is } st\text{-monotone if } \forall i < n \mathbf{P}[s_i, -] \leq_{st} \mathbf{P}[s_{i+1}, -]$$

The survival toolkit: some results

- ▶ Let X, Y be two defective distributions over \mathcal{S} such that $X \leq_{st} Y$ and r be a decreasing mapping over \mathcal{S} . Then: $E(r(X)) \geq E(r(Y))$
- ▶ Let $\mathbf{P} \leq_{st} \mathbf{P}'$ be two sub-stochastic matrices over \mathcal{S} such that either \mathbf{P} or \mathbf{P}' is st -monotone. Then:

1. The inequality holds for every power of matrices: $\forall k \in \mathbb{N} \mathbf{P}^k \leq_{st} \mathbf{P}'^k$
2. (as a corollary) the mean leaving time of \mathbf{P} is greater than the one of \mathbf{P}' :

$$\left(\sum_{k \in \mathbb{N}} \mathbf{P}^k\right) \mathbf{1}_n \geq_{et} \left(\sum_{k \in \mathbb{N}} \mathbf{P}'^k\right) \mathbf{1}_n$$

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Stochastic bounds and IMCs

Motivation

How to compute (accurate) bounds for leaving time $\mathbf{m}[s]$ and $\mathbf{M}[s]$?

$$\mathbf{m}[s] \leq \min_{\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \text{out})} \{(\sum_{k \in \mathbb{N}} \mathbf{P}^k) \mathbf{1}_n\}[s]$$
$$\max_{\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \text{out})} \{(\sum_{k \in \mathbb{N}} \mathbf{P}^k) \mathbf{1}_n\}[s] \leq \mathbf{M}[s]$$

Computing the best $\mathbf{m}[s]$ is straightforward.

$$\min_{\mathbf{P} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \text{out})} \{(\sum_{k \in \mathbb{N}} \mathbf{P}^k) \mathbf{1}_n\}[s] = (\sum_{k \in \mathbb{N}} (\mathbf{P}^-)^k) \mathbf{1}_n[s]$$

Computing a bound $\mathbf{M}[s]$ via stochastic order (*Haddad, Moreaux EJOR 2007*)

- ▶ There is a unique greatest lower bound \mathbf{P}^\bullet w.r.t. \leq_{st} for $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \text{out})$
- ▶ which admits a unique greatest *monotone* lower bounding matrix $\mathbf{P}^\star \leq_{st} \mathbf{P}^\bullet$.
- ▶ $\mathbf{M}[s] = (\sum_{k \in \mathbb{N}} (\mathbf{P}^\star)^k) \mathbf{1}_n[s]$
(*different bounds are possible depending on the ordering of states*)
- ▶ Furthermore a priori detecting states s for which $\mathbf{M}[s] = \infty$ can be performed in very efficient way without computing the strongly connected components of the underlying graph (*this paper*).

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IMC model

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Efficient Model Checking PCTL for IMCs

Conclusion and perspectives

PCTL for MCs

Syntax

$\phi ::= true \mid a \mid \phi \wedge \phi \mid \neg\phi \mid \mathcal{P}_{\triangleleft p}(\mathcal{X}\phi) \mid \mathcal{P}_{\triangleleft p}(\phi_1 \mathcal{U}^{[\alpha,\beta]}\phi_2) \mid \mathcal{D}_{\triangleleft r}(\phi)$

Semantic: path formulas

A path $\sigma \equiv s_0, s_1, \dots$ is an infinite sequence of states of the Markov chain.

- ▶ $\sigma \models \mathcal{X}\phi$ iff $s_1 \models \phi$
- ▶ $\sigma \models \phi_1 \mathcal{U}\phi_2$ iff there exists i such that $s_i \models \phi_2$ and $\forall j < i \ s_j \models \phi_1$

Semantic: state formulas

▶ Threshold formulas

based on $Prob^{\mathcal{M}}(s, \varphi)$ the probability that a random path in \mathcal{M} starting from s satisfies φ

$$s \models \mathcal{P}_{\triangleleft p}(\varphi) \text{ iff } Prob^{\mathcal{M}}(s, \varphi) < p$$

▶ Duration formulas

based on $E^{\mathcal{M}}(FTime(s, \phi))$ the mean of the first time that a random path in \mathcal{M} starting from s satisfies ϕ

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PCTL for IMCs

Exact semantic

1. $\forall \mathcal{M} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+) \mathcal{M}, s \models \phi$ (*always satisfied*)
2. $\forall \mathcal{M} \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+) \mathcal{M}, s \models \neg \phi$ (*never satisfied*)
3. $\exists \mathcal{M}, \mathcal{M}' \in \mathcal{M}(\mathbf{P}^-, \mathbf{P}^+) \mathcal{M}, s \models \phi \wedge \mathcal{M}', s \models \neg \phi$
(*sometimes satisfied and sometimes not*)

Approximate semantic induced by a semi-decisional procedure

Six possible alternative information labels for s w.r.t. ϕ

- ▶ $s.\phi = \forall^+$ when it is known that case 1 holds.
- ▶ $s.\phi = \forall^-$ when it is known that case 2 holds.
- ▶ $s.\phi = \exists^{+-}$ when it is known that case 3 holds.
- ▶ $s.\phi = \exists^+$ when it is known that cases 1 or 3 hold.
- ▶ $s.\phi = \exists^-$ when it is known that cases 2 or 3 hold.
- ▶ $s.\phi = ?$ when no information has been obtained.

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Outline

IMC model

PCTL

3 Efficient Model Checking PCTL for IMCs

Conclusion and perspectives

General principles

First step. Split the set of states depending on:

- ▶ the current label (\forall^+, \dots) to be assigned to states;
- ▶ the labels of states w.r.t. the sub-formulas occurring in the formula;
- ▶ the external path operator of the formula;
- ▶ the kind of comparison \leq, \geq .

Second step. Build one or more sub-stochastic matrices

- ▶ by (appropriately) ordering the states inside the subsets;
- ▶ and applying an algorithm for IMC to compute the coefficients (maximizing cumulative probabilities, *st*-monotone glb matrix, etc.).

Third step. Perform a standard computation for Markov chains.

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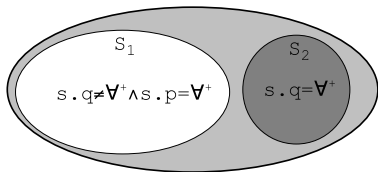
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Assigning \forall^- for formula $\mathcal{P}_{\leq p}(p \mathcal{U}^{[0,\beta]} q)$

First step.

The semi-decision procedure implies a conservative approach. Thus:

- ▶ $\mathcal{S} \setminus (\mathcal{S}_1 \cup \mathcal{S}_2) = \{s \in \mathcal{S} \mid s.p \neq \forall^+ \wedge s.q \neq \forall^+\}$ is the set of states such that one cannot assign \forall^- .
(the probability of satisfaction for the random path could be 0)
- ▶ $\mathcal{S}_2 = \{s \in \mathcal{S} \mid s.q = \forall^+\}$ is the set of states such that one can surely assign \forall^- .
(the probability of satisfaction for the random path is 1)
- ▶ $\mathcal{S}_1 = \{s \in \mathcal{S} \mid s.p = \forall^+ \wedge s.q \neq \forall^+\}$ is the set of states that requires a (conservative) computation.



Assigning \forall^- for formula $\mathcal{P}_{\leq p}(p \mathcal{U}^{[0,\beta]} q)$

Second step.

What is the quantity to lower bound?

The probability to reach \mathcal{S}_2 from \mathcal{S}_1 without leaving \mathcal{S}_1 in at most β steps:

$$\left(\sum_{k=0}^{\beta-1} (\mathbf{P}_{|\mathcal{S}_1 \times \mathcal{S}_1})^k \right) \cdot \mathbf{r}$$

where $\mathbf{r}[s]$ is the probability to immediately reach \mathcal{S}_2 from s .

So we perform the following substitutions:

- ▶ Matrice \mathbf{P}^- is substituted to \mathbf{P} .
- ▶ Vector \mathbf{r} is substituted by $\mathbf{r}^- = \max(\sum_{s' \in \mathcal{S}_2} \mathbf{P}^-[s, s'], 1 - \sum_{s' \notin \mathcal{S}_2} \mathbf{P}^+[s, s'])$

Third step. Compute $\mathbf{m} = \left(\sum_{k=0}^{\beta-1} (\mathbf{P}_{|\mathcal{S}_1 \times \mathcal{S}_1}^-)^k \right) \cdot \mathbf{r}^-$

and assign \forall^- to s iff $\mathbf{m}[s] > p$.

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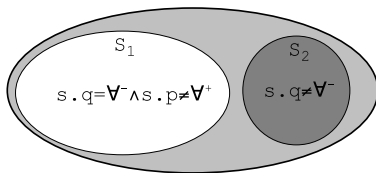
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Second step.

We now upper bound

$$\left(\sum_{k=0}^{\beta-1} (\mathbf{P}|_{\mathcal{S}_1 \times \mathcal{S}_1})^k \right) \cdot \mathbf{r}$$

So we define an appropriate $\mathcal{M}(\mathbf{P}^-, \mathbf{P}^+, \mathbf{out})$ over \mathcal{S}_1 :

- ▶ Matrices $\mathbf{P}^+, \mathbf{P}^-$ are the original matrices restricted to \mathcal{S}_1 .
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$$\mathbf{out}[s] = \max(\sum_{s' \notin \mathcal{S}_1} \mathbf{P}^- [s, s'], 1 - \sum_{s' \in \mathcal{S}_1} \mathbf{P}^+ [s, s'])$$
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$$\mathbf{M} = \left(\sum_{k=0}^{\beta-1} (\mathbf{P}^*)^k \right) \cdot \mathbf{r}^+$$

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Assigning \exists^+ for formula $\mathcal{P}_{\leq p}(p \mathcal{U}^{[0,\beta]} q)$

First step as in the previous case.

Second step.

Here we guess one (or more) matrix \mathbf{P} with a small value of:

$$\left(\sum_{k=0}^{\beta-1} (\mathbf{P}|_{\mathcal{S}_1 \times \mathcal{S}_1})^k \right) \cdot \mathbf{r}$$

- ▶ We order the states of \mathcal{S} : first \mathcal{S}_2 then \mathcal{S}_1 and $\mathcal{S} \setminus (\mathcal{S}_1 \cup \mathcal{S}_2)$
- ▶ Inside \mathcal{S}_1 , order the states w.r.t.
 $\mathbf{r}[s] = \max(\sum_{s' \in \mathcal{S}_2} \mathbf{P}^+[s, s'], 1 - \sum_{s' \notin \mathcal{S}_2} \mathbf{P}^+[s, s'])$
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Outline

IMC model

PCTL

Efficient Model Checking PCTL for IMCs

4 Conclusion and perspectives

Conclusion and perspectives

Summary of results

- ▶ Efficient semi-decision procedure for model checking IMCs
- ▶ Application of stochastic comparisons for model checking PCTL over IMCs
- ▶ Handling the interval constrained until and the mean reachability time operators
- ▶ Providing partial answers \exists^+ , \exists^-

Perspectives

- ▶ Development of a prototype for high level formalisms with IMC as possible semantic
- ▶ Accuracy of bounds and impact of heuristics
- ▶ One year post-doc position available for this project