

Steady State Dependability Verification by Perfect Sampling

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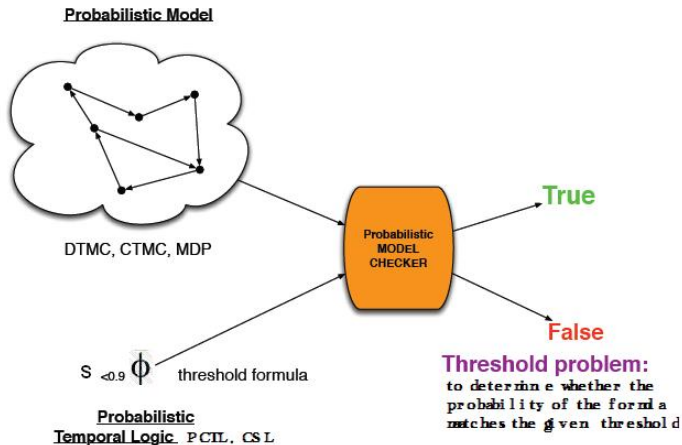
Outline

- 1 Introduction**
 - Probabilistic Model Checking
 - Perfect Sampling
- 2 SMC using Perfect Sampling**
 - SMC Decision Method
 - SMC of CSL Steady State Formula
- 3 Experimental Comparison Study**
 - Case studies
 - Compared Tools
 - Experimental Results
- 4 Conclusion and Future works**

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Probabilistic Model Checking



Probabilistic Model Checking

1 Probabilistic Models

- CTMC, DTMC, MDP, ...
- Queueing Networks, Network protocols, Distributed Systems

2 Dependability, availability and reachability properties with probabilistic temporal logics

- CSL for CTMC, PCTL for DTMC
- Steady State Operator: $\mathcal{S}_{\geq\theta}(\phi)$

Ex: With probability at least θ , a system will be available at long run (in steady-state)

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Solution Methods

1 Numerical Model Checking (NMC)

- Based on: **Computation** of distributions
- + Highly accurate results
- Intractable for systems with large state space

2 Statistical Model Checking (SMC)

- Based on: **Sampling** (by simulation or by measurement) and **Statistical Methods** for verification
- + Low memory requirements
- Expensive if high accuracy is required

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Existing Model Checkers

- 1 PRISM tool: **Numerical**
 - Matrix representation: memory limit
- 2 MRMC tool: **Statistical**
 - Simulation by regeneration method
 - Same memory limit problem as PRISM
- 3 Ymer, VESTA tools: **Statistical**
 - *transient properties*
- 4 APMC tool: **Statistical**
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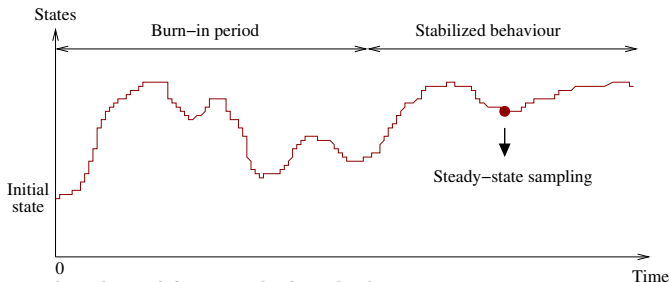
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Stochastic simulation idea



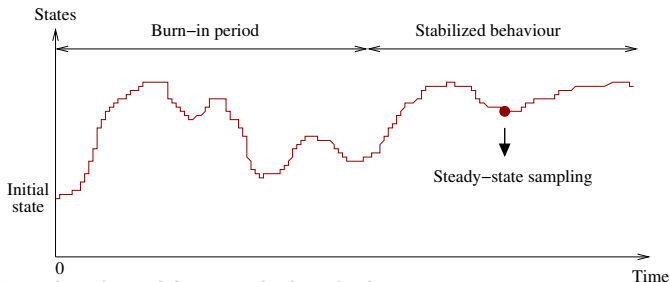
■ Drawbacks of forward simulation

- Steady state is **not exact**
- Dependence on the initial state
- Burn-in period estimation
⇒ **Biased sampling**

■ Alternatives

- Regeneration (MRMC tool)
- Perfect sampling (Ψ^2 tool)

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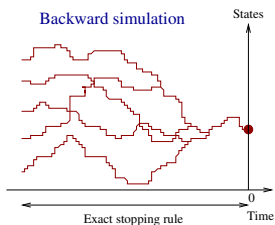
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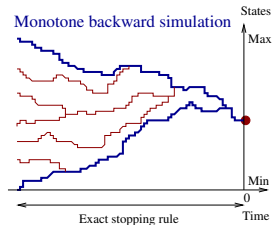
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Backward Simulation Schemes

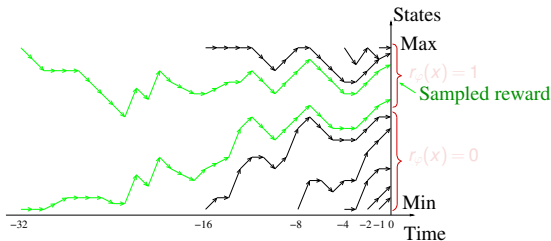
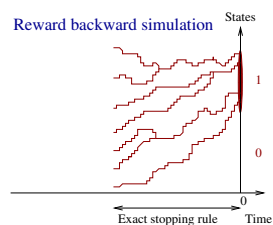
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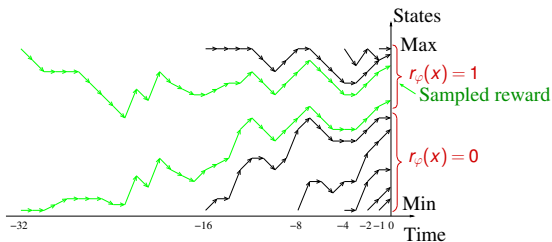
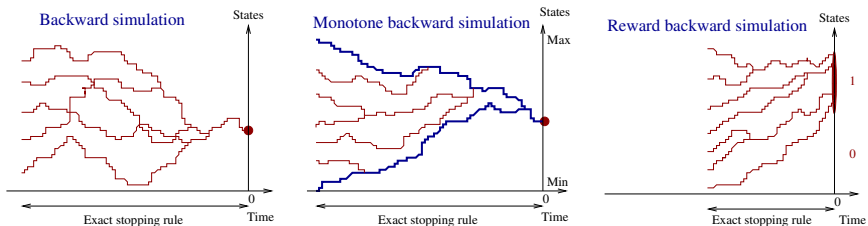
Monotone backward simulation



Reward backward simulation



Backward Simulation Schemes



Synthesis

■ Advantages

- Steady state is **exact** (perfect sample)
- **Unbiased sampling** of the steady-state
- Very efficient under monotonicity
- Very efficient for rare probability verification
- Generic events (monotone and not) implemented in ψ^2 enabling to describe a wide range of systems

■ Drawbacks

- Monotonicity study of a system
 - If system is monotone: has to be proven
 - If not, "extended sandwiching technique": envelopes (not always efficient)
- A perfect sampler ψ^2 proposed by MESCAL INRIA Team
 - Samples rewards of the stationary distribution of large Markov chains

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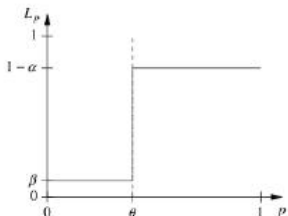
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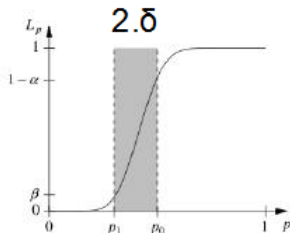
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Statistical Hypothesis Testing (SHT)

- Estimate the probability p that φ of a given formula $S_{\geq\theta}(\varphi)$ is satisfied on sample paths
- Formula verification: Test $H : p \geq \theta$ against $K : p < \theta$
- For specified indifference region δ and error bounds (α, β)



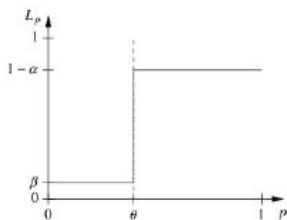
(a) Prob. of accepting H
(ideal)



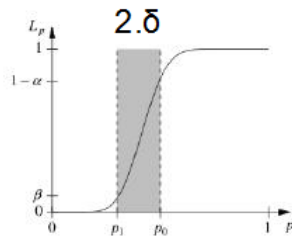
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(b) Prob. of accepting H
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Decision Method

- 1 Inspired from the Single Sampling Plan (SHT method used by Younes et al.)
- 2 Check samples and compute number of positive samples (Y)

$$H_0 : p \geq \theta + \delta \quad H_1 : p < \theta - \delta$$

- If $Y \geq m$ then accepting H_0 (YES)
 - Else If $Y < m$ then accepting H_1 (NO)
 - where m is the acceptance threshold of the statistical test
- 3 Statistical test strength (n, m) depends on (α, β) and on δ where n is the total sample size

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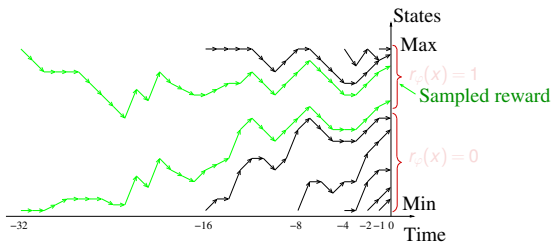
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Verification of CSL Steady State Formula

- SMC of $\psi = \mathcal{S}_{\geq \theta}(\varphi)$ by functional and/or monotone perfect simulation
- Check if the steady-state samples (x) satisfies φ or not
- By associating reward $r_\varphi(x)$ to each state x for the given property φ :

$$r_\varphi(x) = 1, \text{ if } x \models \varphi \quad (1)$$

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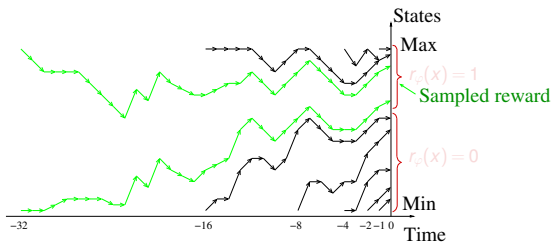


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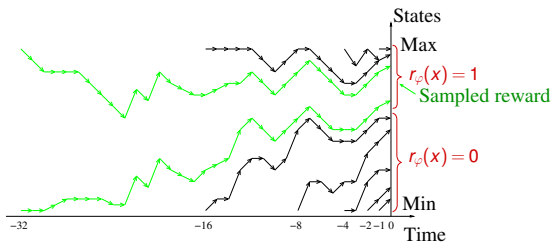


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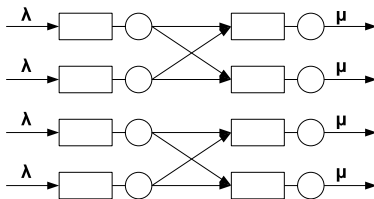


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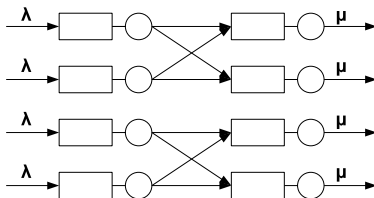
Models

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 - Monotone model (ψ^2 benchmark)
- 2 Multistage delta queueing network with 8 queues (MDN)
 - Monotone model (ψ^2 benchmark)



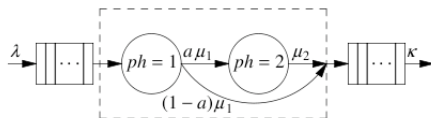
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Tandem Queuing Network with coaxian server (TQN-Cox)

- Non monotone model (PRISM benchmark)
- Implemented in ψ^2 using envelopes



Verified Properties (1)

- 1** AP $a_i(k)$: True if $N_i > k$, False otherwise
 - N_i : number of customers in the i^{th} queue
 - $0 \leq k \leq N_{\max}$ and N_{\max} : maximum queue size
- 2** Define different saturation and availability measures for the underlying models
 - Ex: Saturation property in the i^{th} buffer, $S_{<\theta}(a_i(N_{\max}))$, also check availability property $S_{\geq 1-\theta}(\neg a_i(N_{\max}))$

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Verified Properties (2)

- 1 Tandem network with 4 queues (TN)
 - 4th buffer is full ($< \theta$ or not at steady state)
- 2 Multistage delta queueing network with 8 queues (MDN)
 - At least one queue of the second stage of MDN is full ($< \theta$ or not at steady state)
- 3 Tandem Queueing Network with coaxian server (TQN-Cox)
 - The overall system is full ($< \theta$ or not at steady state)

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- 1 PRISM tool (Numerical MC, Oxford University)
 - Computes probabilities for each reachable state
 - Solves system of linear equations to find probabilities with convergence **precision ϵ**
- 2 ψ^2 with SHT tool (SMC, Grenoble and UPEC Universities)
 - Perfect sampling (Functional)
 - Verification by Statistical Hypothesis Testing with **precision (α, β, δ)**
- 3 Comparison study
 - For fair comparison we take **$\epsilon = 2.\delta$**
 - $(\epsilon, \delta) = \{(10^{-3}/2, 10^{-3}/4), (10^{-4}, 10^{-4}/2)\}$ and $\alpha = \beta = 10^{-2}$
 - Rare probability dependability properties: **$\theta = 0.001$**

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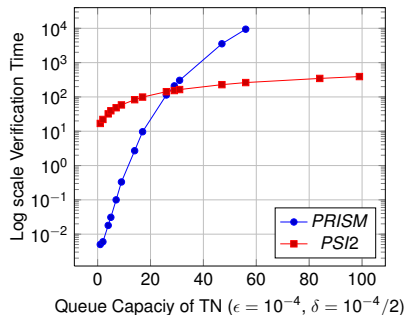
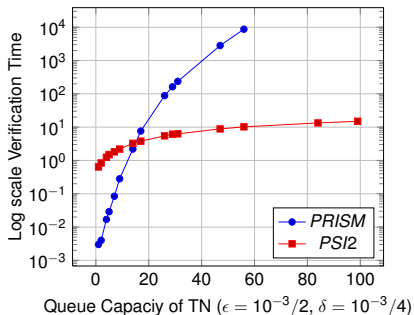
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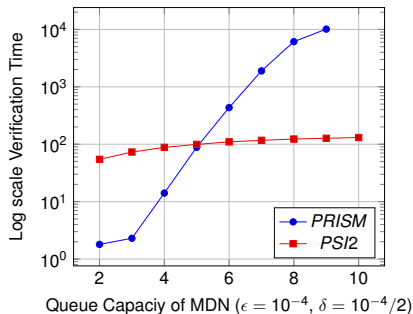
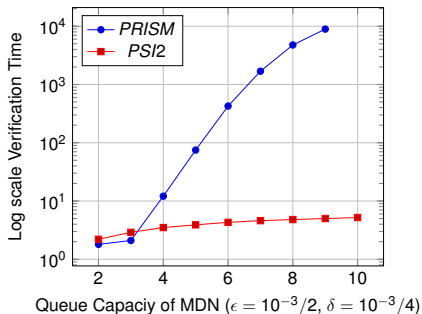
Tandem Network (TN)

- Model and property: $\lambda = 0.9$, $\mu_i = 1$, $1 \leq i \leq 4$,
 $S_{<\theta}$ (*last-full*) where $\theta = 0.001$



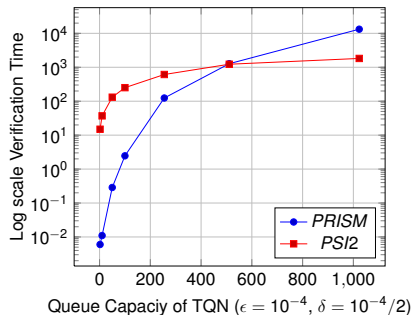
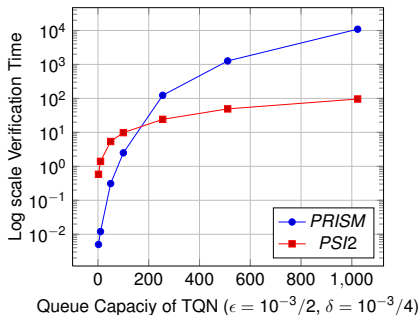
Multistage Delta Network (MDN)

- Model and property: 2 stages and 4 buffers/stage,
 $\lambda = 0.9$, $\mu = 1$, $(\tau_{rout1}, \tau_{rout2}) = (0.8, 0.6)$,
 $S_{<\theta}$ (last-stage-full) where $\theta = 0.001$



Tandem Queueing Network (TQN)

- Model and property: $\lambda = 4 \times N_{max}$, $\mu_1 = 2$, $\mu_2 = 2$, $a = 0.1$ and $\kappa = 4$, $S_{<\theta}$ (*sys-full*) where $\theta = 0.001$



Synthesis and Discussions

- 1** Variation of precision parameters ϵ (numerical) and δ (statistical)
 - Verification time **dependence on** δ is **considerable** but on ϵ is **negligible**
- 2** Variation of state space size (Max. queue capacity)
 - + Verification time **dependence on** state space size is **negligible** in ψ^2 (functional) but is **considerable** in PRISM
- 3** Memory limitation problem
 - + Memory is **never exhausted** in ψ^2 but is proportional to the number of states in PRISM

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- 1 Memory limits obtained in PRISM:
 - TN case: For $N_{max} = 99$ ($|X| = 10^8$)
 - MDN case: For $N_{max} = 10$ ($|X| = 1.1 * 10^8$)
 - TQN case: For $N_{max} = 7500$ ($|X| = 2.1 * 10^8$)
- 2 MDN case: For 4 *stages* and 8 *buffers/stage*
 - + Efficient results using Ψ^2 while not possible using PRISM (memory problem for $N_{max}=1$, $O((N_{max} + 1)^{32})$)
- 3 TQN case (Non monotone model)
 - + Efficient results for this example when using envelopes

Conclusion

1 Empirical comparison of numerical and statistical solutions

- PRISM vs. ψ^2 with SHT
- Focus on CSL steady state formulas

2 We have found that:

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- + ψ^2 with SHT is **faster** than PRISM for **large models** (greater than 10^5)
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Conclusion

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- 1 Compare ψ^2 with SHT tool with the MRMC tool (Current)
 - Perfect Simulation vs. Regeneration Simulation
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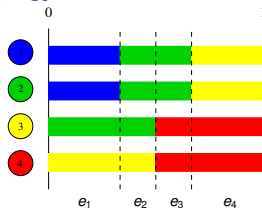
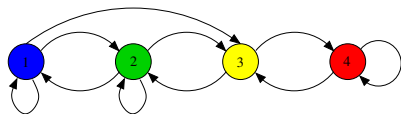
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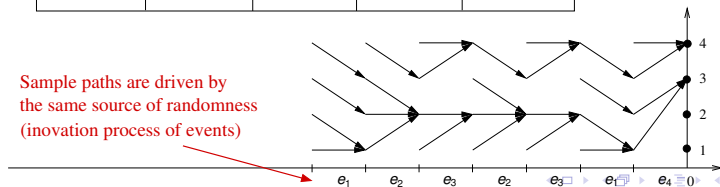
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Event modelling of a Markov chain



event	e_1	e_2	e_3	e_4
probability	$\frac{2}{6}$	$\frac{1}{6}$	$\frac{1}{6}$	$\frac{2}{6}$
Transition function $\Phi(x, \cdot)$	$\begin{array}{l} 4 \rightarrow 4 \\ 3 \rightarrow 3 \\ 2 \rightarrow 2 \\ 1 \rightarrow 1 \end{array}$	$\begin{array}{l} 4 \rightarrow 4 \\ 3 \rightarrow 3 \\ 2 \rightarrow 2 \\ 1 \rightarrow 1 \end{array}$	$\begin{array}{l} 4 \rightarrow 4 \\ 3 \rightarrow 3 \\ 2 \rightarrow 2 \\ 1 \rightarrow 1 \end{array}$	$\begin{array}{l} 4 \rightarrow 4 \\ 3 \rightarrow 3 \\ 2 \rightarrow 2 \\ 1 \rightarrow 1 \end{array}$

Sample paths are driven by the same source of randomness (innovation process of events)



Monotonicity

Monotone event

- let \preceq be a partial order on a multi-dimensional state space $\mathcal{X} = \mathcal{X}_1 \times \dots \times \mathcal{X}_K$ (usually a lattice).

$$x \preceq y \Leftrightarrow x^i \leq y^i \quad \forall i$$

- An event e is monotone if it preserves the partial ordering \preceq on \mathcal{X}

$$\forall (x, y) \in \mathcal{X} \quad x \preceq y \Rightarrow \Phi(x, e) \preceq \Phi(y, e)$$

Monotonicity of systems

A Markov chain is monotone if all events are monotone