Probabilistic Model Checking with Perfect Simulation

Diana EL RABIH Nihal PEKERGIN

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Outline

- Introduction
 - Probabilistic Model Checking
 - Model Checking of CTMCs using CSL
 - CSL formulas
 - Numerical vs Statistical
- 2 Previous Work
 - Statistical Model Checking
 - Perfect Simulation
- 3 Motivations and Objective
- Our Contribution
 - SMC Decision and Precision
 - SMC of CSL Steady State Operator
 - SMC of CSL Unbounded Until formula

Probabilistic Model Checking Model Checking of CTMCs using CSL CSL formulas Numerical vs Statistical

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Probabilistic Model Checking

- Automatic formal verification technique for the analysis of systems which exhibit stochastic behavior.
- Given a model M, a state s, and a property Φ, does Φ hold in s for M?
 - Model: Continuous-time Markov Chain
 - Property: Continuous Stochastic Logic (CSL) formula
- Solution methods:
 - Numerical: computation of distributions
 - Statistical:
 - Sampling (by simulation or by measurement)
 - Hypothesis Testing

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Model Checking of CTMCs using CSL

Model checking of stochastic systems

- Continuous-time Markov chains CTMC
- Continuous Stochastic Logic (CSL)
- State formulas
 - Truth value is determined in a single state
- Path formulas
 - Truth value is determined over a path

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CSL formulas

- Standard logic operators: $\neg \phi \mid \phi_1 \land \phi_2 \ldots$
- Probabilistic operator: $\mathcal{P}_{\geq \theta}(\rho)$
 - Holds in state s iff probability is at least θ that ρ holds over paths starting in s
- Time bounded Until: $s \models \mathcal{P}_{\geq \theta}(\phi \ \mathcal{U}^T \ \psi)$
 - Holds over path *σiff*ψ becomes true along *σ* within time T, and φ is true until then
 - If T=[0, ∞) then $s \models \mathcal{P}_{\geq \theta}(\phi \ \mathcal{U} \ \psi)$ is unbounded until
- Steady State Operator: $S_{\geq \theta}(\phi)$

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Numerical vs Statistical Model Checking

Numerical Method

- Highly accurate results
- Expensive for systems with many states

Statistical Method

- Low memory requirements (state explosion problem)
- Expensive if high accuracy is required

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Statistical Model Checking Perfect Simulation

Concept of SMC

- Statistical approach is based on
 - Generating sample paths by simulation or by measurement
 - Hypothesis Testing
- We cannot guarantee that the verification result is correct
 - But we can at least bound the probability of generating an incorrect answer to a verification problem
- A key observation of SMC interest is that
 - It is not necessary to obtain an accurate estimate of a probability in order to verify probabilistic properties

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Hypothesis Testing in SMC

- In SMC approach a model checking problem can be seen as hypothesis testing problem to verify probabilistic properties
- To verify a given property
 - Test the hypothesis H : p < θ against the alternative hypothesis K : p ≥ θ
- SMC approach permits to estimate the probability that a given formula is satisfied on sample paths
 - for specified confidence interval, confidence level and error bounds

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Statistical Model Checking Perfect Simulation

Existing SMC Approaches

- Randomised approximation scheme proposed by Peyronnet and al.
- Statistical hypothesis testing of Younes and al. was studied CSL time bounded formulas
 - Based on discrete event simulation and on acceptance sampling
 - Extended to the case of black box systems
- Statistical Model Checking of Sen and al. was studied in addition unbounded until CSL formula
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Statistical Model Checking Perfect Simulation

Perfect Simulation Global Idea

- Perfect Simulation based on coupling from the past
 - Monte Carlo method
 - directly generates a sample according to the stationary distribution of Markov Chains
 - Avoids burn-in time period
- Perfect simulation is efficient when the model is monotone
 - Trajectories initiating from set of maximal and minimal states
- When all sample-paths couple, a sample state is obtained
 - by running simulation from distant point in the past until the present
 - in order to obtain a perfect sample at coupling

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Perfect Sampler ψ^2

- ψ² proposed in MESCAL Project is a sampler designed for the steady state evaluation of various monotone queueing networks
 - Following a sampler ψ of Markov chains for the perfect sampling of Markov chains without monotonicity properties
- ψ^2 permits to simulate stationary distribution or directly a cost function of large Markov chains
 - By keeping only trajectories issued from the minimal and maximal states

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Our Motivations

- Numerical methods suffer from state space explosion problem
- Statistical methods have low memory requirements and then do not suffer from the state space explosion problem
- CSL Steady State operator was not studied before in other SMC approaches
- CSL Unbounded Until was studied by Sen and al in their SMC method
 - But suffering from stopping probability problem because they cannot detect the steady state in their approach
- While Perfect Simulation permits to detect the steady state
 - Then permits to avoid stopping probability problem

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Our Objective

Probabilistic model checking of stochastic systems modelled by Markov Chains

- Using statistical approach
- By applying Perfect Simulation which is a Monte Carlo method
- To verify CSL Steady State operator and CSL Unbounded Until formula
- This method is efficient
 - when underlying model is monotone
 - when CSL state formula is increasing (functional)
 - These hypothesis are not so restrictive and satisfied in general for performance and reliability models

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On SMC Approach Precision

- A sample of size n obtained by perfect sampler consists of n observations: *X*₁, *X*₂, ..., *X*_n (Bernoulli variables)
 - Pr[X_i=1]=Pr[pos sample]=p'
 - Pr[X_i=0]=Pr[neg sample]=1-p'
- Hypothesis Testing in SMC approach
 - Testing $H_0: p' < \theta \delta$ ($s \not\models \phi$) against $H_1: p' \ge \theta + \delta$ ($s \models \phi$)
 - If $Y = \frac{\sum_{i=1}^{n} X_i}{n} \ge \theta$ then H_1 is accepted and H_0 is rejected, otherwise H_0 is rejected and H_1 is accepted
- Y has binomial distribution then
 - $\Pr[Y \le m] = F(m, n, p') = \sum_{i=1}^{m} C(n, i)(p')^{i}(1-p')^{n-i}$
 - Where $m=n.\theta$: acceptance threshold
- Then resulting test has the strength depending on error bounds α (significance level) and β

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On Perfect Simulation Precision

- We look for bounds on true mean μ, with finite number of samples
 - By finding b_1 and b_2 such that $\Pr(b_1 < \mu < b_2) = 1-\gamma$
 - [b₁, b₂]: confidence interval
 - 100(1-γ): confidence level
- The confidence interval of a simulation output is given by $M \pm t.s/\sqrt{n}$
 - M : sample mean, s : estimation of the standard deviation and t : constant determined from t distribution table
- In perfect simulation, because of the independence of generated values:
 - The length of the confidence interval at 95% level is majorized by 1.68 s/ \sqrt{n} where n is the sample size

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Proposed SMC Decision Algorithm

Input: Property ψ , Model M, threshold θ , total nb of samples nbsamptotal, indifference region δ Output: YES or NO or Don't Know

Initialize nbsampos to zero

- Test of the positive samples from 1 to total number of samples and then calculate number of positive samples
- 3 Let Y=nbsampos/nbsamptotal, H₀ : p' < θ − δ and H₁ : p' ≥ θ + δ where p'=prob[Xi=1]
- If Y ≥ θ then deciding YES and making decision by accepting H₁ with c% confidence level, otherwise deciding NO and making decision by accepting H₀ with (1-c)% confidence level

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- Solution Let Y=nbsampos/nbsamptotal, $H_0 : p' < \theta \delta$ and $H_1 : p' \ge \theta + \delta$ where p'=prob[Xi=1]
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SMC Decision and Precision SMC of CSL Steady State Operator SMC of CSL Unbounded Until formula

Proposed SMC Decision Algorithm

Input: Property ψ , Model M, threshold θ , total nb of samples nbsamptotal, indifference region δ Output: YES or NO or Don't Know

- Initialize nbsampos to zero
- Test of the positive samples from 1 to total number of samples and then calculate number of positive samples
- Solution Let Y=nbsampos/nbsamptotal, $H_0 : p' < \theta \delta$ and $H_1 : p' \ge \theta + \delta$ where p'=prob[Xi=1]
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SMC Decision and Precision SMC of CSL Steady State Operator SMC of CSL Unbounded Until formula

Precision of SMC Decision Algorithm

- How to determine confidence level c?
 - 2 contraints are required in the hypothesis testing context:
 - $\Pr[H_1 \text{ is accepted } | H_0 \text{ is true}] \leq \alpha$
 - $\Pr[H_0 \text{ is accepted } | H_1 \text{ is true}] \leq \beta$
 - Practically the true mean μ estimated by $Y = \frac{\sum_{i=1}^{n} X_i}{n} \ge \theta$, is included in the confidence interval $[Y \delta, Y + \delta]$ where Y is the sample mean of the perfect sampling and δ =1.68 s/ \sqrt{n}
 - α is determined from respecting constraint F (m, n, p_0) = α
 - where F (m, n, p)= $\sum_{i=1}^{m} C(n, i)p^{i}(1-p)^{n-i}$, $p_{0} = \theta - \delta$, $p_{1} = \theta + \delta$ and m=n. θ
- Thus c can be determined by applying c=100(1- α)%

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SMC Decision and Precision SMC of CSL Steady State Operator SMC of CSL Unbounded Until formula

Outline

Probabilistic Model Checking Model Checking of CTMCs using CSL • CSL formulas Numerical vs Statistical Statistical Model Checking Perfect Simulation **Our Contribution** SMC Decision and Precision SMC of CSL Steady State Operator

SMC of CSL Steady State Operator

Conclusion

Verification Principle of CSL Steady State Operator

- States of CTMC M are labelled with AP that will be used to define the underlying property ϕ to check
 - underlying model
- The checking procedure consists in
 - Finding the sum of the probabilities of the states verifying ϕ
 - Comparing this sum with the probability threshold θ
 - - Then the steady state operator is verified by M

SMC of CSL Steady State Operator

Conclusion

Verification Principle of CSL Steady State Operator

- States of CTMC M are labelled with AP that will be used to define the underlying property ϕ to check
 - ϕ may represent different performance measures of the underlying model
- The checking procedure consists in
 - Finding the sum of the probabilities of the states verifying ϕ
 - Comparing this sum with the probability threshold θ
 - If the comparison relation between the determined sum and θ is verified
 - Then the steady state operator is verified by M

SMC Decision and Precision SMC of CSL Steady State Operator SMC of CSL Unbounded Until formula



- This summation of the probabilities of the states verifying ϕ can be seen
 - as a reward function defined on the state space
 - where r_{ϕ} =1 if $s \models \phi$ and r_{ϕ} =0 if $s \not\models \phi$
- Next we propose to apply a method called functional perfect simulation to check the given formula ϕ on each generated sample
 - by means of software ψ^2
 - by supposing the monotonicity of the considered reward function r_ϕ

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Proposed Algorithm for CSL Steady State Operator

Set time t to 1 and Repeat steps 1, 2, 3 until coupling on reward function (all rewards will be equal)

- Initialize time t to 2.t and initiate trajectories for all x ∈ setof Max U setof min
- 2 Generate new events from t downto t/2+1
- Output State S
- Finally, if the reward of the perfect sample is equal to 1 then return 1 (studied sample is a positive sample), otherwise return 0 (studied sample is a negative sample)

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Verification Principle of CSL Unbounded Until

- Unbounded until φ₁ Uφ₂ can be obtained as a special case of the bounded ones by taking I= [0,∞)
- Numerically checking principle
 - Probability measure for an until formula is equivalent to the transient probability at time t of the ϕ_2 states on the CTMC M from making every $(\neg \phi_1 \lor \phi_2)$ state absorbing
- Statistically checking principle
 - Testing states s by starting from initial state and continuing test while state s verifies φ₁ until we achieve a state s verifying φ₂ at steady state or before this state

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SMC Decision and Precision SMC of CSL Steady State Operator SMC of CSL Unbounded Until formula

Proposed Algorithm for CSL Unbounded Until

Set time t to 1 and Repeat while STOP=false

- Initialize time t to 2.t and initiate trajectories for all $x \in$ initial state s_0 U setof Max U setof min
- ② Generate new events from t downto t/2+1
- Loop from t downto 1 while STOP=false
 - Generate the trajectories T_{s0}, T_{min}andT_{Max} by considering events E[t], E[t-1], , E[1]
 - For $x \in$ initial state s_0 U setof Max U setof min test
 - If trajectory Tx meets a state non verifying ϕ_1 then STOP will be True and affect the returned test result to 1
 - Else if trajectory Tx meets a state verifying ϕ_2 then STOP will be True and affect the returned test result to 0
- Finally, if STOP remains false then we have to test the steady state case
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El Rabih, Pekergin

Probabilistic Model Checking with Perfect Simulation



- Our statistical model checking algorithms that we have developed for stochastic models have at least three advantages over previous works
 - can model check CSL formulas which have unbounded untils and steady state
 - do not suffer from memory problem due to state-space explosion
 - CSL unbounded until model checking algorithm does not suffer from stopping probability problem
 - because of possibility of steady state detection in our approach



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However, our algorithms also have at least two limitations

- cannot guarantee the accuracy that numerical techniques achieve
- running time will increase if we try to increase the accuracy by making the error bounds or confidence level very small
- Thus statistical model checking technique can be seen as
 - an alternative to numerical techniques
 - can be be used when it is infeasible to use numerical techniques, for example, in large-scale systems as ad hoc and sensor networks



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